

## Theory of Pseudo Cross-Link

### 3. Rheological Behavior

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#### Summary

Stress-relaxation, creep and stress-strain relations are discussed in terms of pseudo cross-link concept. The decrease of cross-links by the stress or strain leads to an equation similar to the Mooney-Rivlin equation. Viscous flow is also an important factor decreasing the cross-sectional area of the specimen and the chain-extension. Viscosity much decreases with increasing rate of extension and temperature. Filler ingredient plays roles of not only enhancing the chain strain but also providing the pseudo cross-link due to adsorption of the rubber on the filler surface.

#### Theory

##### 1. Decrease of pseudo cross-link by extension

Static behavior of solid polymers such as stress-relaxation, creep and stress-strain relations can be interpreted on the basis of the pseudo cross-link concept. For the cross-linked rubber the elastic force  $f$  (dyne/cm<sup>2</sup>) acting on the original cross-sectional area  $A = 1$  cm<sup>2</sup> at an extension ratio  $\lambda$  is given as follows;

$$f = \nu kTA(\lambda - 1/\lambda^2) \quad (1)$$

where  $\nu$  is the number of cross-links or the number of chains existing in a unit volume or 1 cm<sup>3</sup> of a specimen.

For non-vulcanized rubber  $\nu$  is taken to be the number of pseudo cross-links  $\nu_2$  and is variable with the time  $t$  and represented simply by equation

$$(2) \quad \nu = \nu_2 = \nu_e + (\nu_0 - \nu_e) e^{-k't} \quad (2)$$

where  $\nu_0$  is an equilibrium value at the initial stage under no stress and  $\nu_e$  is that at the final stage under stress.  $k'$  is a rate constant of break down of the pseudo cross-link per second.

At the same time the decrease of pseudo cross-link is accompanied by the decrease of the cross-sectional area and chain extension. The cross-sectional area decreases from the initial area  $A_0$  to the area  $A$  at the time

t. The chain extension ratio  $\lambda$  is smaller than the extension ratio of the specimen  $\alpha$ . They are given from figure 1. The end-to-end distance of the chain, its elongation and the number of the chain along the extension direction are given by  $(N/\nu_0)^{1/2}$ ,  $\alpha$  and  $(\nu_0/N)^{1/3}$ , respectively, and the length of the specimen is equal to their product. After the change of the pseudo cross-link from  $\nu_0$  to  $\nu$ , these values change respectively to  $(N/\nu)^{1/2}$ ,  $\lambda$  and  $(\nu/N)^{1/3}$  for the same length of the specimen, and consequently

$$\begin{aligned} (N/\nu_0)^{1/2} \alpha (\nu_0/N)^{1/3} &= (N/\nu)^{1/2} \lambda (\nu/N)^{1/3} \\ \text{or} \quad A/A_0 &= \lambda/\alpha = (\nu/\nu_0)^{1/6} = e^{-k't/6} \end{aligned} \quad (3)$$

Substituting equations (2) and (3) into (1), the stress is given as

$$\begin{aligned} f/kT &= \{ \nu_e + (\nu_0 - \nu_e) e^{-k't} \} (A/A_0) (\lambda/\alpha) (\alpha - 1/\alpha^2) \\ &= \{ \nu_e + (\nu_0 - \nu_e) e^{-k't} \} e^{-k't/3} (\alpha - 1/\alpha^2) \end{aligned} \quad (4)$$

It is also noticed that the rate constant  $k'$  is much affected by the force or strain which decreases the activation energy for the break down of the cross-link of size  $b$ , i.e.  $bE_0^*$  by the work done  $W$ . Namely,

$$k' \propto \exp \{ - (bE_0^* - W)/RT \} \quad (5)$$

The work done  $W$  is given by a product of the force, the cross-sectional area  $(n^{1/2} \ell)^2$  and the loosen bond length  $\delta \ell$  and the size of pseudo cross-link  $b$  as shown in figure 2

$$W = f (n^{1/2} \ell)^2 \delta \ell \times b N_0 \quad (6)$$

where  $n$ ,  $\ell$  and  $N_0$  are the number of segments of a chain, the diameter of a segment and Avogadro's number, respectively and  $\delta$  is assumed to be 0.04 as mentioned before. Substituting the following relations

$$\begin{aligned} f &= \nu kT (\lambda - 1) \\ n &= N/\nu \quad \text{and} \quad \ell^3 = 1/N \end{aligned}$$

$$\text{it follows that} \quad k' = k_0' e^{b\delta(\lambda - 1)} \approx k_0' \delta b \lambda \quad (7)$$

where

$$k_0' = (kT/h) n_B^{-3} e^{-bE_0^*/RT}$$

The size  $b$  lies between 4 and 16. Equation (7) implies that  $k'$  becomes larger as the chain extension ratio  $\lambda$  increases.

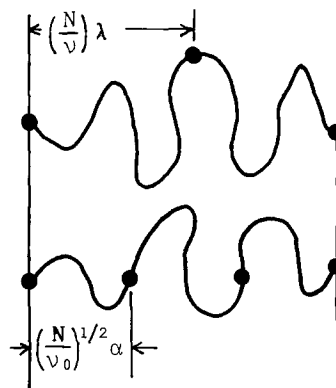


Fig.1 Relation between  $\lambda$  and  $\alpha$

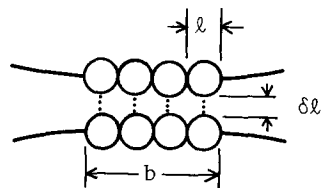


Fig. 2 Pseudo cross-link in the loosen state

## 2. Pseudo cross-links of multiple size

Since the cross-link of the size  $b$  possesses  $b$ -times larger value of the heat of formation  $\Delta H$ , the entropy loss  $\Delta S$  and the activation energy  $E^*$  than those of the unit link,  $\Delta H_0$ ,  $\Delta S_0$  and  $E_0^*$ , respectively, the fraction of the  $b$ -size cross-link  $\nu_b/N$  and its relaxation time  $\tau_b$  are given by equations (8) and (9), respectively.

$$\nu_b/N = \exp\{b(-\Delta H_0/RT + \Delta S_0/R)\} \quad (8)$$

$$\tau_b = 1/k_b' = (h/kT)n_B^3 \exp(bE_0^*/RT) \quad (9)$$

Eliminating  $b$  from equations (8) and (9), a dynamic spectrum of the cross-link  $\nu$  or the elasticity  $E$  against the relaxation time  $\tau$  is obtained as a function of temperature.

$$\log(E/E_A) = \log(\nu/N) = (-\Delta H/E_0^*)(1 - T/T_A) \log(\tau_A/\tau) \quad (10)$$

where  $E_A$  and  $\tau_A$  are values for the unit size cross-link  $A$ .  $T$  is an experimental temperature and  $T_A$  is a transition temperature given by  $\Delta H_0/\Delta S_0$ .

As mentioned previously another transition temperature  $T_B$  for the flow exists, which is equal to  $1.5T_A$ , and at near  $T_B$ , equation (10) is rewritten as

$$E/E_A = \nu/\nu_A = (\tau_A/\tau)^{1/2} \quad (11)$$

For the multiple size network the cross-links having sizes smaller than  $b$  are relaxed during the time  $t$  equal to  $\tau_b$  and the fraction of the remaining cross-link is given by equation (12).

$$\nu/\nu_0 = (\tau_0/\tau)^{1/2} = (\tau_0/t)^{1/2} \quad (12)$$

where  $\nu_0/N$  and  $\tau_0$  are the initial fraction of the cross-links and their relaxation time, respectively.  $\tau_0$  is also affected by the strain and expressed by equation (13).

$$\tau_0 = (1/k_0') e^{-\delta b(\lambda - 1/\lambda^2)} = 1/\delta b \lambda k_0' \quad (13)$$

Substituting equation (13) into equation (12) and taking that the extension ratio of chain  $\lambda$  is equal to that of the specimen  $\alpha$  and the rate of extension is  $\dot{\alpha}$  or  $\alpha/t$ , it follows that

$$f/f_0 = (k_0' t)^{-1/2} = (\dot{\alpha}/\delta b k_0')^{1/2} (1/\alpha) \quad (14)$$

Under stress the successive break down of the pseudo cross-link takes place. The force at break is assumed to be represented as a product of the fractional number of the remaining pseudo cross-link  $\nu_2/N$ , the fraction of pseudo cross-link having more than the bond energy  $-\Delta H$  in a total chain energy given by  $\lambda^2 RT$  and the bond force constant given by  $d(-\Delta H/\lambda^2)/d\lambda \cong -\Delta H/V_0$ ,  $V_0$  being a molar volume of the segment.

$$f = (\nu_2/N) \exp\{-(-\Delta H/\lambda^2 RT)\}(-\Delta H/V_0) \quad (15)$$

Equation (15) possesses the maximum at

$$\lambda = (-\Delta H/RT)^{1/2} \quad (16)$$

For the unit pseudo cross-link  $(\text{CH}_2)_2$ ,  $-\Delta H$  is 1360 cal and equation (16) becomes to

$$\lambda = (1.36/0.6)^{1/2} = 1.5$$

at 0.6 Kcal of RT. This value is close to the value obtained by taking  $v_0/N$  to 1/2.

$$\lambda = (N/v_0)^{1/2} = \sqrt{2} = 1.4$$

A chain composed of two or three units is assumed to be linked with a pseudo cross-link composed of two or three units as the chain of the minimum size.

### 3. Rheological equations

Equation (14) derives several rheological relations.

(1) Stress-strain relation — From equations (4) and (14), equation (17) is obtained

$$f/(\alpha - 1/\alpha^2) = kT\{(v_0 - v_e)(\dot{\alpha}/\delta k_0')^{1/2}/\alpha + v_e\} \quad (17)$$

which corresponds to the useful phenomenological relation of Mooney and Rivlin<sup>2</sup>, i.e.,

$$f/(\alpha - 1/\alpha^2) = 2C_1 + 2C_2/\alpha \quad (18)$$

In fact, the plots of  $f/(\alpha - 1/\alpha^2)$  against  $1/\alpha$  gives a straight line in various cases not only for vulcanized rubbers, but also for unvulcanized rubbers. The meaning of  $C_1$  and  $C_2$  have been discussed by several authors but the pseudo cross-link concept also gave a likely explanation.<sup>3</sup>  $C_1$  and  $C_2$  are given as follows

$$2C_1 = (v_1 + v_e) kT \quad (19)$$

$$\text{and} \quad 2C_2 = (v_0 - v_e)(\dot{\alpha}/\delta k_0')^{1/2} kT \quad (20)$$

where  $v_1$  is the number of the chemical cross-link for the vulcanized rubber. Equation (20) suggests that  $C_2$  increases as the rate of extension increases and  $k_0'$  or the temperature is lowered. This fact was confirmed by the authors.<sup>3</sup> However,  $C_2$  becomes constant when  $\dot{\alpha}/k_0'$  becomes unity, and in this case equation (17) is written as

$$f/(\alpha - 1/\alpha^2) = kT\{(v_0 - v_e)/\alpha + v_e\} \quad (21)$$

It is noticed that equation (18) is valid for the value of  $\alpha$  above 1.4. For the vulcanized rubber there is an upper limit arising from the limited extensibility of the chain dependency on the degree of vulcanization. Figures 3 and 4 illustrate the profile of the stress-strain relation, where the curve a refers to equation (19) and b refers to the curve for vulcanized rubbers.

(2) Stress-relaxation — Taking  $\alpha$  to be a constant in equation (15),  $f$  is given as

$$f/f_0 = (1/k't)^{1/2} \quad (22)$$

which indicates that the stress decreases with  $t^{1/2}$ .

(3) Creep under a constant load — Taking  $f$  to be a constant  $f_0$ ,  $\alpha$  is

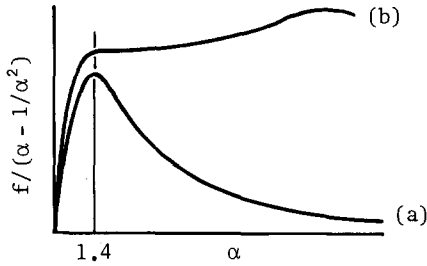


Fig. 3 Unvulcanized (a) and vulcanized rubber (b)

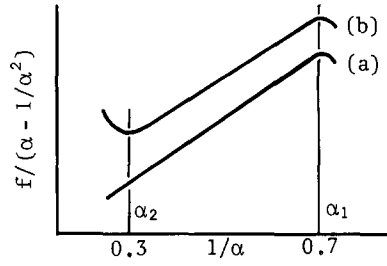


Fig. 4 Mooney-Rivlin plot for unvulcanized (a) and vulcanized rubber (b)

given as follows.

$$\alpha - 1/\alpha^2 = (f/v_0kT)(k't)^{1/2} \tag{23}$$

However, if the effect of the stress on the rate constant  $k'$  is considered,

$$\frac{f_0/kT}{\alpha - 1/\alpha^2} = \left(\frac{v_0 - v_e}{\alpha}\right) \left(\frac{1}{\delta k_0'}\right)^{1/2} \left(\frac{d\alpha}{dt}\right)^{1/2} + v_e$$

For a small value of  $v_e$

$$\alpha^3/3 - 2 \ln\alpha - 1/5\alpha^5 = \left\{ \frac{\delta k_0'}{(v_0 - v_e)^2} \frac{f_0}{kT} \right\} t \tag{24}$$

which indicates that  $\alpha$  increases proportionally with  $t^{1/3}$ .

(4) Recovery after release from load — Taking  $f$  to be zero in equation (15), it follows that

$$\begin{aligned} d\alpha/dt &= -\{v_e/(v_0 - v_e)\}^2 \delta k_0' \alpha^2 \\ 1/\alpha &= 1/\alpha_B + \{v_e/(v_0 - v_e)\}^2 \delta k_0' t \end{aligned} \tag{25}$$

which indicates that  $\alpha$  decreases inversely proportionally with  $t$ ,  $\alpha_B$  being an elongation ratio at a turn-back point B.

4. Viscous flow resistance

The elastic deformation accompanied by the decrease of the pseudo cross-links involves the viscous flow of chain and it is represented as a product of the viscosity  $\eta$ , the rate of deformation  $\dot{\alpha}$  and a factor due to the deformation  $\alpha$  as follows. As illustrated in figure 5, the length increases from  $L$  to  $L\alpha$  and the cross-sectional area decreases from  $L^2$  to  $L^2/\alpha$  as the specimen is elongated. The relation between the velocity gradient and the shear force is represented as

$$\frac{\Delta u}{L/\sqrt{\alpha}} = \frac{f(L/\alpha)^2}{\eta(L\alpha)(L/\sqrt{\alpha})} \tag{26}$$

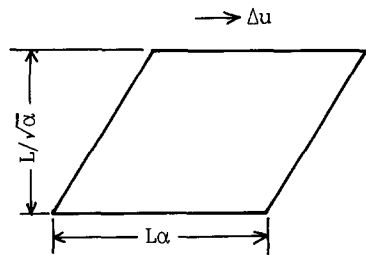


Fig. 5 Velocity gradient

Since the velocity difference  $\Delta u$  is equal to

$L\dot{\alpha}$ , the viscous force  $f_v$  becomes to

$$f_v = f/\alpha = \eta \dot{\alpha} \alpha = (v_2kT/k') \dot{\alpha} \alpha \tag{27}$$

However, the viscous force induced by the extension is involved in the

elastic force and is not revealed unless  $f_v$  is larger than the elastic force. In the latter case the tensile deformation results in the plastic rupture. On the contrary, the deformation in a closed vessel the continuous viscous flow occurs and the viscous force  $f_v$  is not given by equation (27) but by equation (28).

$$f_v = \eta \dot{\alpha} \quad (28)$$

For example, the viscous flow in the capillary no correction is necessary since the length of the specimen is kept constant in the capillary.

The viscosity is affected by the deformation for two reasons: one is the acceleration of the break-down of the pseudo cross-link by the elongation of the chain and  $k'$  is increased from  $k'_0$  as pointed out in equation (13) and is represented as

$$k' = k_0 \exp \{ \delta b(\lambda - 1) \} \quad (29)$$

Another reason is the change of chain length due to the decrease of the pseudo cross-links. The average chain length  $n$  is given by

$$n = N/v_2 \quad (30)$$

And  $n$  is increasing with decreasing number of the pseudo cross-link and when  $n$  becomes less than the critical length of  $n_B$  assumed to be  $10^{2.4}$  as pointed out in the paper 2,  $k'$  is affected by the chain length as represented as

$$k' (n_B/n)^{3.5} = k' (v_2/v_B)^{3.5} \quad (31)$$

where  $v_B$  is the number of critical pseudo cross-link. The viscosity  $\eta$  is

$$\eta = (v_B kT/k') (v_B/v_2)^{3.5} \quad (32)$$

And at the stationary state  $n$  becomes to  $n_0$ , i.e., the segmental length of the whole molecule and equation (32) becomes to

$$\eta = (v_B kT/k'_0) (n_B/n_0)^{3.5} \exp\{-\delta b(\lambda - 1)\} \quad (33)$$

Equation (33) is rewritten as a function of the force, i.e.,  $f = \eta \dot{\alpha}$  as

$$\eta = \eta_0 \exp(-\eta \dot{\alpha}/v_B kT) = \eta_0 \exp(-\eta \dot{\alpha}/\eta_0 k'_0) \quad (34)$$

where  $\eta_0$  is the viscosity at no shear rate or

$$\eta_0 = (v_B kT/k'_0) (n_B/n_0)^{3.5} n_B^3 \quad (35)$$

Equation (34) is transformed into a simple form for the structural viscosity

$$\eta/\eta_0 = 1/(1 + \dot{\alpha}/k'_0) \propto \dot{\alpha}^{-n} \quad (36)$$

where

$$n = 1 - \log(1 + \dot{\alpha}/k'_0)/\log \dot{\alpha} \quad (37)$$

The order of  $n$  was found to be  $0.7 \sim 0.9$  for rubber.

### 5. Effect of filler

Fillers such as carbon black and clay enhance the elasticity of the polymers. The effect may be ascribed to two reasons: One is that fillers decreases the volume fraction of the polymer and as a result the actual deformation of the molecular chain becomes larger than the apparent deformation of the specimen. The second reason may be the formation of

the pseudo cross-link between the filler surface and the surrounding molecular chain.

The former volume effect is calculated as follows. For the volume fraction of filler  $x$ , the tensile elongation of the specimen  $\alpha$  is given by the sum of the tensile fraction of the polymer whose elongation is  $\lambda$  and that of the filler and accordingly, equation (33) holds.

$$\alpha = (1 - x)^{1/3} \lambda + x^{1/3} \cong (1 - x)^{1/3} \lambda \quad (33)$$

Consequently, the actual extension  $\lambda$  is represented as

$$\lambda \cong \alpha / (1 - x)^{1/3} \quad (34)$$

The additional pseudo cross-link due to the adsorption on the filler is given by a product of the volume fraction of fillers  $x$  and their specific number of pseudo cross-link on a unit fraction of the filler,  $V_f$  and the latter is proportional to the specific surface area, i.e., a reciprocal radius of the filler particule  $1/r$  and the strength of adsorption given by  $\exp(-\Delta H_f/RT)$  where  $\Delta H_f$  is an exothermic heat of adsorption.

$$x V_f \propto (1/r) \exp(-\Delta H/RT) \quad (35)$$

Taking these effects into consideration equations (17) and (27) may be rewritten as follows

$$f/kT = \left\{ \frac{v_0 - v_e}{\alpha} e^{-k'\phi t/3} + x \frac{v_{f0} - v_{fe}}{\alpha} e^{-k'\phi_f t/3} \right\} \alpha \quad (36)$$

and

$$f_V/kT = (v_2/k' + x V_f/k'_f) \dot{\alpha} \alpha \quad (37)$$

where the suffix  $f$  refers to the filler and  $\alpha$  is taken to be  $\alpha(\text{actual})/(1-x)^{1/3}$ .

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